

## Meaning of Stokes Theorem:

Stokes Theorem:

$$\iint_S \text{Curl } \vec{F} \cdot \hat{n} dS = \oint_C \vec{F} \cdot \vec{T} ds$$

$\oint_S$  Flux of the  $\text{Curl } \vec{F}$  thru  $S$

$\oint_C$  line integral around boundary

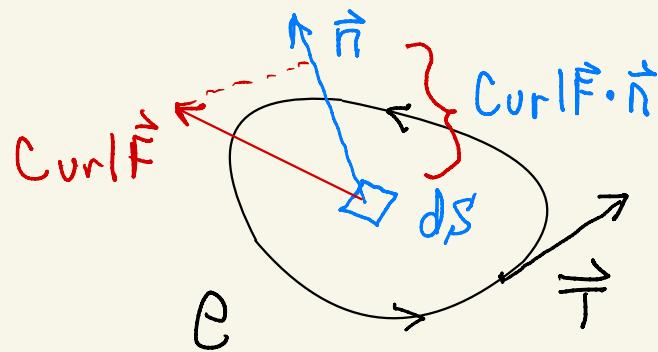
Example: Verify

Stokes Theorem in

case  $S$  = hemisphere

$$x^2 + y^2 + z^2 = 9, z \geq 0$$

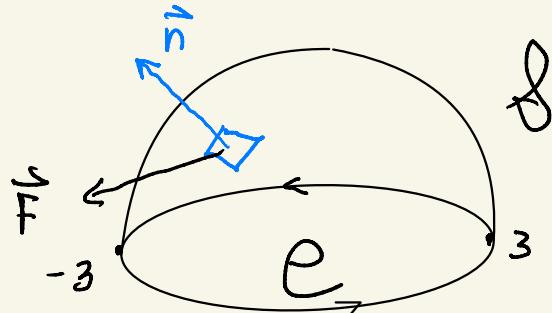
$$\vec{F} = y \hat{i} - x \hat{j}$$



Soln: The boundary Curve for the hemisphere

$$\text{IS: } C = x^2 + y^2 = 3$$

• First we calculate RHS:



$$\oint_C \vec{F} \cdot \vec{T} ds = \iint_S M dx + N dy = \int_0^{2\pi} 3y(-\sin t) - 3x \cos t dt$$

$t = \theta$   
 $x = 3 \cos t$     $y = 3 \sin t$   
 $0 \leq t \leq 2\pi$

$dx = -3 \sin t dt$   
 $dy = 3 \cos t dt$

$$= 9 \int_0^{2\pi} -\sin^2 t - \cos^2 t dt = -9 \cdot 2\pi = \boxed{-18\pi}$$

• Now calculate LHS:  $\iint_S \text{Curl} \vec{F} \cdot \vec{n} dS$  (2)

$$\text{Curl} \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y & -x & 0 \end{vmatrix} = \hat{k} (-1 - 1) = -2 \hat{k}$$

$$\vec{r}(x, y) = \overrightarrow{(x, y, \sqrt{9 - x^2 - y^2})}$$

$$\vec{n} = \frac{x \hat{i} + y \hat{j} + z \hat{k}}{\sqrt{x^2 + y^2 + z^2}} = \frac{x \hat{i} + y \hat{j} + z \hat{k}}{3}$$

because  
S is on  
sphere

$$\text{Curl} \vec{F} \cdot \vec{n} = (-2 \hat{k}) \cdot (x \hat{i} + y \hat{j} + z \hat{k}) \frac{1}{3} = -\frac{2}{3} z$$

Spherical Coordinates:  $u = \phi, v = \theta$

$$\vec{r}(\phi, \theta) = \overrightarrow{3(\cos \theta \sin \phi, \sin \theta \sin \phi, \cos \phi)}$$

We have:  $A = |\vec{r}_\phi \times \vec{r}_\theta| = 3^2 \sin \phi$  (From map problem -)  
or just compute

$$\iint_S \text{Curl} \vec{F} \cdot \vec{n} dS = \iint_S -\frac{2}{3} z dS = \int_0^{\pi/2} \int_0^{2\pi} -\frac{2}{3} z 3^2 \sin \phi d\theta d\phi$$

$\uparrow 3 \cos \phi$

$$= -\frac{2}{3} 3^3 (2\pi) \int_0^{\pi/2} \cos \phi \sin \phi d\phi = -36\pi \left[ \frac{\sin^2 \phi}{2} \right]_0^{\pi/2} = -18\pi$$

$u = \sin \phi$   
 $du = \cos \phi d\phi$

(3)

Example (2) Use Stokes to obtain the correct interpretation of  $\text{Curl } \vec{F}$  as "circulation per area in  $\vec{F}$ "

Soln.: Let  $\vec{F}$  be a vector field. Recall that

$\oint_C \vec{F} \cdot \vec{T} ds$  is the "circulation in  $\vec{F}$  around  $C$ "

because it measures the component of  $\vec{F}$  tangent to  $C$ , weighted with arclength  $ds$ , and summed around the curve  $C$ .

So... take a small disc  $D_\epsilon$  of

radius  $\epsilon > 0$ , oriented with

normal  $\vec{n}$ , placed at a point  $\vec{x} = (x, y, z)$ .

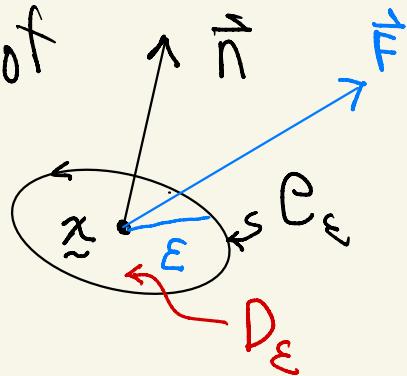
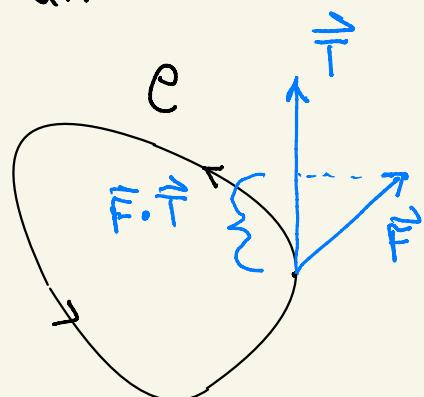
Let  $C_\epsilon$  be the boundary circle of  $D_\epsilon$ , oriented by AHR with  $\vec{n}$ .

Now apply Stokes Theorem:

$$\iint_{D_\epsilon} \text{Curl } \vec{F} \cdot \vec{n} dS = \oint_C \vec{F} \cdot \vec{T} ds$$

$D_\epsilon$

We wonder what  
 $\text{Curl } \vec{F} \cdot \vec{n}$  measures



We know this is  
circulation in  $\vec{F}$  around  $C$

Now for the trick: assuming  $\vec{F}$  is smoothly varying, (say continuous derivatives) we know that as  $\epsilon \rightarrow 0$ , the value of  $\text{Curl } \vec{F} \cdot \vec{n}$  in  $D_\epsilon$  is very close, i.e. tends to its value at the center, namely,  $\text{Curl } \vec{F} \cdot \vec{n}(\vec{x})$ . Thus we can approximate  $\text{Curl } \vec{F} \cdot \vec{n}$  as constant, and pull it out of  $\iint$ , only incurring a small error which will be negligible as  $\epsilon \rightarrow 0$ .

$$\text{I.e. } \iint_{D_\epsilon} \text{Curl } \vec{F} \cdot \vec{n} dS = \underbrace{\text{Curl } \vec{F} \cdot \vec{n}(\vec{x})}_{\substack{\text{what we are} \\ \text{trying to} \\ \text{interpret}}} \iint_{D_\epsilon} dS + \underbrace{\text{error}}_{\substack{\text{smaller than } |D_\epsilon|}} \quad \text{Area of } D_\epsilon = |D_\epsilon| = \pi \epsilon^2$$

Thus from Stokes Theorem:

$$\iint_{D_\epsilon} \text{Curl } \vec{F} \cdot \vec{n} dS = \text{Curl } \vec{F} \cdot \vec{n}(\vec{x}) |D_\epsilon| + \text{error} = \oint_{C_\epsilon} \vec{F} \cdot \vec{T} ds$$

Divide thru by  $|D_\epsilon| \dots$

$$\text{Curl } \vec{F} \cdot \vec{n}(\vec{x}) = \frac{1}{|D_\epsilon|} \oint_{C_\epsilon} \vec{F} \cdot \vec{T} ds - \frac{\text{error}}{|D_\epsilon|} \quad \text{tends to zero as } \epsilon \rightarrow 0$$

Thus:  $\text{Curl} \vec{F} \cdot \vec{n}(x) = \lim_{\epsilon \rightarrow 0} \frac{1}{|D_\epsilon|} \oint_{C_\epsilon} \vec{F} \cdot \vec{T} ds$

(Applies to any area  
 $D_\epsilon$  oriented by normal  $\vec{n}$ )

circulation per area

Conclude: The value of  $\text{Curl} \vec{F} \cdot \vec{n}$  at a point  $x$   
measures the circulation per area in  $\vec{F}$   
around the axis  $\vec{n}$ .

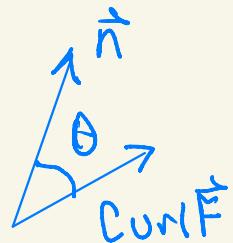


Example ③ Around which axis  $\vec{n}$  does  $\vec{F}$   
exhibit maximum circulation?

Ans:  $\text{Curl} \vec{F} \cdot \vec{n} = \|\text{Curl} \vec{F}\| \|\vec{n}\| \cos \theta$

which is maximum when  $\cos \theta = 1$ ,  $\theta = 0$ ,

So the axis  $\vec{n}$  around which  $\vec{F}$  circulates  
most rapidly is  $\vec{n} = \frac{\text{Curl} \vec{F}}{\|\text{Curl} \vec{F}\|}$ , ie the  
direction of  $\text{Curl} \vec{F}$ !



Example ④ What does the length of  $\text{Curl} \vec{F}$  measure?

Ans : The maximum circulation per area occurs around axis  $\vec{n} = \frac{\text{Curl} \vec{F}}{\|\text{Curl} \vec{F}\|}$ , the magnitude being

$$\text{Curl} \vec{F} \cdot \vec{n} = \text{Curl} \vec{F} \cdot \frac{\text{Curl} \vec{F}}{\|\text{Curl} \vec{F}\|} = \frac{\|\text{Curl} \vec{F}\|^2}{\|\text{Curl} \vec{F}\|} = \|\text{Curl} \vec{F}\|$$

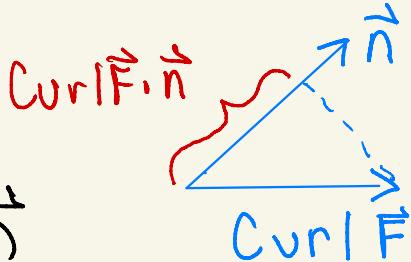
= maximum circulation per area

Conclude :  $\text{Curl} \vec{F}$  gives the axis around which  $\vec{F}$  is circulating most rapidly, and its length is the magnitude of maximum circulation !

Note : The component of  $\text{Curl} \vec{F}$  in any unit direction  $\vec{n}$  gives circulation per area around  $\vec{n}$

$$(\text{Circulation per area around } \vec{n}) = \text{Curl} \vec{F} \cdot \vec{n} = \|\text{Curl} \vec{F}\| \cos \theta$$

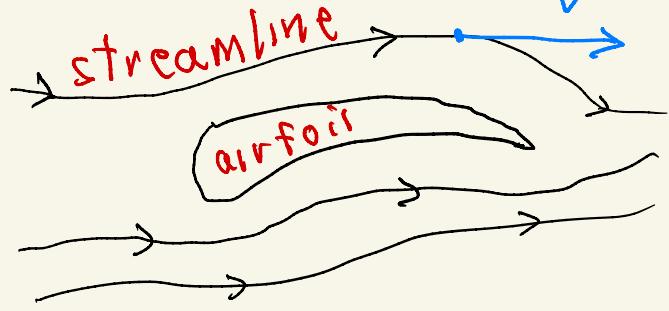
= Component of  $\text{Curl} \vec{F}$  in direction of unit vector  $\vec{n}$



■ Application: The curl as "revolutions per second" = frequency in fluid model - 7

Assume  $\vec{F} = \vec{V}$  = velocity in fluid model of a density  $\delta(x, y, z)$  moving at velocity  $\vec{v} = \vec{v}(x, y, z, t)$

I.e. a streamline  $\vec{r}(t)$  is the curve taken by a fluid particle, and the velocity vector  $\vec{v}(x) = \vec{r}'(t)$  for the streamline thru  $x = (x, y, z)$



Q: What does  $\text{Curl } \vec{v}$  measure at pt  $(x, y, z)$  ?

Ans:  $\text{Curl } \vec{v} \cdot \vec{n} = 4\pi w$  where  $w = \frac{\text{revolutions}}{\text{sec}}$  of a bead circulating on a circular wire  $C_\epsilon$  oriented by  $\vec{n}$  assuming  $\vec{v} \cdot \vec{T}$  gives the velocity (i.e., no friction, no loss of momentum) in limit  $\epsilon \rightarrow 0$ .

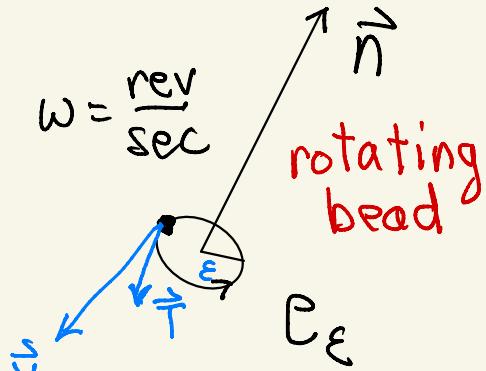
Check: Dimensions  $[v_x] = \frac{1}{L} [v] = \frac{1}{T} \vec{v} \cdot \vec{n}$  rotating bead  
 $[\text{Curl } \vec{v} \cdot \vec{n}] = [\text{Curl } \vec{v}] [\vec{n}] = \frac{1}{T}$   $C_\epsilon$   
 $\frac{1}{L} \frac{1}{T} \quad 1$  dimension of frequency

$\left( \frac{[\vec{v}]}{[\vec{w}]} \right) = \frac{[\vec{v}]}{[\vec{w}]} = 1 \Rightarrow \text{unit vectors are dimensionless} \right)$

Example ⑤: Verify  $\operatorname{Curl} \vec{v} \cdot \vec{n} = 4\pi \omega$  8

$$\text{Soln: } \text{Curl } \vec{v} \cdot \hat{n} \underset{\substack{\uparrow \\ \text{Stokes}}}{\approx} \frac{\text{Circulation}}{\text{area}}$$

$$= \frac{1}{\pi \epsilon^2} \int_{C_\epsilon} \vec{V} \cdot \vec{T} \, ds$$



area  
(The approximate equality  $\approx$  becomes = in limit  $\varepsilon \rightarrow 0$ )

But

$$\begin{aligned}
 \text{ut} \\
 \int_{C_\varepsilon} \vec{v} \cdot \vec{T} ds &= \int_0^{2\pi} \vec{v} \cdot \vec{T} \varepsilon d\theta \\
 \vec{v} \cdot \vec{T} = \frac{ds}{dt} &= 2\pi \varepsilon \frac{1}{2\pi} \int_0^{2\pi} \vec{v} \cdot \vec{T}(\theta) d\theta \\
 = \frac{\text{dist}}{\text{time}} \text{ of bead} \text{ around } C_\varepsilon & \quad \vec{v} = \text{average speed} \quad \frac{ds}{dt}
 \end{aligned}$$

$$= 2\pi \epsilon \bar{V}$$

## Check:

$$\frac{1}{b-a} \int_a^b f(t) dt = \frac{1}{N \Delta t} \lim_{N \rightarrow \infty} \sum_{n=1}^N f(t_n) \Delta t_n = \lim_{N \rightarrow \infty} \frac{\sum_{n=1}^N f(t_n)}{N}$$

average of  $f$

Conclude:  $\text{Curl } \vec{v} \cdot \vec{n} \approx \frac{1}{\pi \epsilon^2} 2\pi \epsilon \bar{v} = \frac{2}{\epsilon} \bar{v}$  9

Now: at average speed  $\bar{v}$ , the bead makes one revolution around  $2\pi \epsilon$  = circumference of  $\epsilon$  in time period  $T$  where

$$2\pi \epsilon = \bar{v} \cdot T \Rightarrow T = \frac{2\pi \epsilon}{\bar{v}}$$

$$\text{dist} = \frac{\text{dist}}{\text{time}} \cdot \text{time}$$

Thus:  $\frac{\# \text{rev}}{\text{sec}} = \frac{1}{\text{time of one rev}} = \frac{1}{T} = \frac{\bar{v}}{2\pi \epsilon} = \omega$

Conclude:

$$\omega = \frac{\bar{v}}{2\pi \epsilon}, \quad \text{Curl } \vec{v} \cdot \vec{n} = \frac{2}{\epsilon} \bar{v}$$

$$\bar{v} = 2\pi \epsilon \omega \Rightarrow \text{Curl } \vec{v} \cdot \vec{n} = \frac{2}{\epsilon} 2\pi \epsilon \omega = 4\pi \omega \quad \checkmark$$

Summary: In the fluid model, the  $\text{Curl } \vec{v}$  gives axis of maximal rotation of a bead constrained to move around a circular wire oriented  $\perp \text{Curl } \vec{v}$ . The length  $\|\text{Curl } \vec{v}\|$  then gives the maximal frequency of rotation, and  $\text{Curl } \vec{v} \cdot \vec{n}$  gives frequency of rotation around axis  $\vec{n}$ .

In Fluid Mechanics:  $\text{Curl } \vec{v}$  = Vorticity. Vorticity plays a fundamental role in the theory of fluids.

Example 6 Assume a fluid is moving with velocity vector  $\vec{F} = \vec{v} = x\hat{i} + xy\hat{j} + \frac{y}{z}\hat{k}$   $\frac{m}{s}$  ( $\frac{m}{s} = \frac{\text{meters}}{\text{sec}}$ ) (10)

- (1) Find axis of maximal rotation at  $P = (1, -1, 2) = \vec{x}_0$ .
- (2) Find the maximal circulation/area
- (3) Find the frequency  $\omega$  and period  $T$  for a bead rotating with  $\vec{v}$  around a circle of radius  $\epsilon$ , center  $\vec{x}_0$ , around axis  $\vec{A} = \overrightarrow{(2, -1, 1)}$ .

Soln (1)  $\text{Curl } \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & 0 & xy\hat{z} \end{vmatrix} = \hat{i}(xz - 0) - \hat{j}(yz - 0) + \hat{k}(0 - 0)$   
 $= x\hat{i} - y\hat{j}$

$$\text{Curl } \vec{F} = \overrightarrow{(xz, -yz, 0)}$$

@  $\vec{x}_0 = (1, -1, 2)$ ,  $\text{Curl } \vec{F} = \overrightarrow{(2, 2, 0)}$

$$\therefore \text{axis of maximal rotation } \vec{n} = \frac{\text{Curl } \vec{F}}{\|\text{Curl } \vec{F}\|} = \frac{\overrightarrow{(2, 2, 0)}}{\sqrt{4+4+0}} = \frac{\overrightarrow{(1, 1, 0)}}{\sqrt{2}}$$

(2) Maximal Circulation per area  $= \|\text{Curl } \vec{F}\| = \sqrt{8} = 2\sqrt{2}$

occurs around axis  $\vec{n} = \frac{\overrightarrow{(1, 1, 0)}}{\sqrt{2}}$

(3) For  $\vec{F} = \vec{v} \frac{m}{s}$ ,  $\text{Curl } \vec{v} = \overrightarrow{(xz, -yz, 0)}$ ,  $\text{Curl } \vec{v} \cdot \vec{n} = 4\pi \omega$

$$\omega = \frac{1}{4\pi} \text{Curl } \vec{v} \cdot \vec{n} (\vec{x}_0) = \frac{1}{4\pi} \overrightarrow{(2, 2, 0)} \cdot \frac{\vec{A}}{\|\vec{A}\|} = \frac{1}{4\pi} \frac{\overrightarrow{(2, 2, 0)} \cdot \overrightarrow{(2, -1, 1)}}{\sqrt{4+1+1}} = \frac{2}{4\pi \sqrt{6}} = \frac{1}{2\pi \sqrt{6}}$$

Ans:  $\omega = \frac{1}{2\pi \sqrt{6}} \frac{1}{s}$ ,  $T = \frac{1}{\omega} = \sqrt{6}\pi \text{ seconds}$

## ■ Why Stokes Theorem is true -

Stokes Theorem:  $\iint_S \text{Curl} \vec{F} \cdot \hat{n} dS = \oint_C \vec{F} \cdot \vec{T} ds$

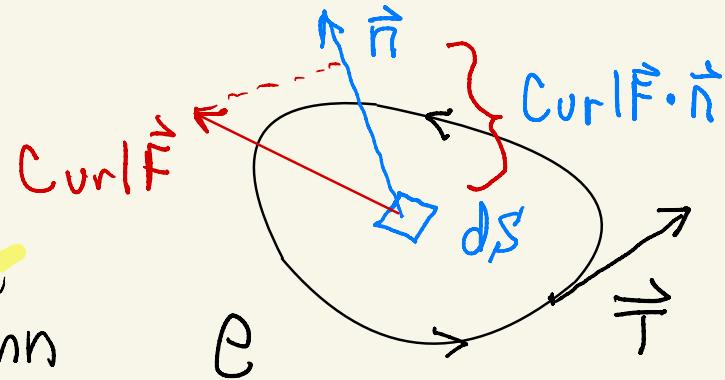
Q: Why is it true?

Ans: Because  $\text{Curl} \vec{F} \cdot \hat{n}$

is the circulation per area,

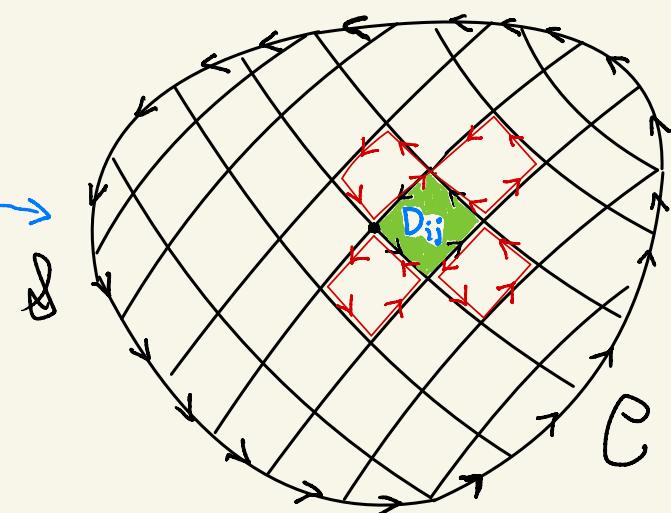
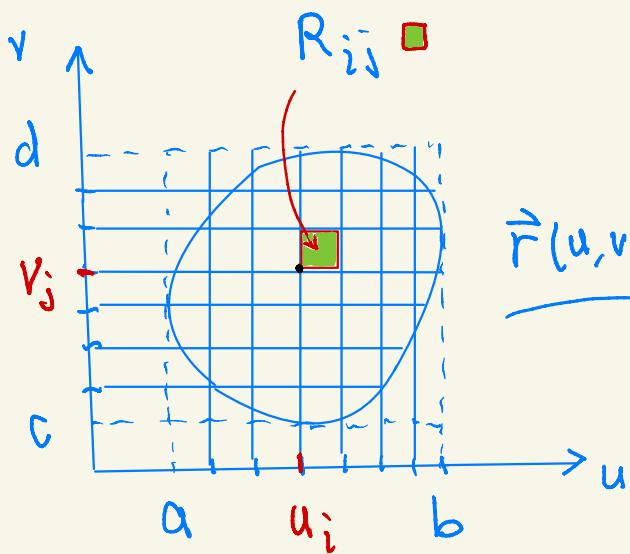
so when we write a Riemann

Sum for  $\iint_S \text{Curl} \vec{F} \cdot \hat{n} dS$ , each element  $D_{ij}$  reduces to a line integral around its boundary, and all the interior adjacent line integrals cancel out because they have opposite orientation.



I.e.,  $\iint_S \text{Curl} \vec{F} \cdot \hat{n} dS = \lim_{N \rightarrow \infty} \left| \sum_{ij} \iint_{D_{ij}} \text{Curl} \vec{F} \cdot \hat{n} dS = \sum_{ij} \sum_{C_{ij}} \int_{C_{ij}} \vec{F} \cdot \vec{T} ds \right|$

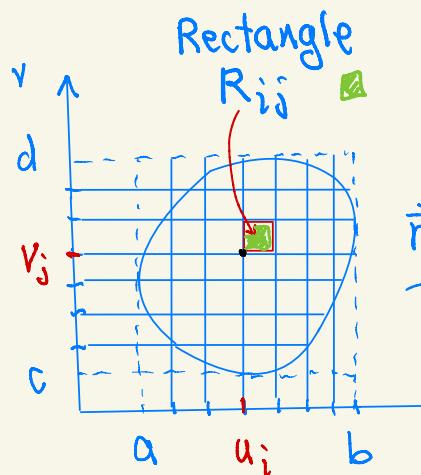
$$= \oint_C \vec{F} \cdot \vec{T} ds$$



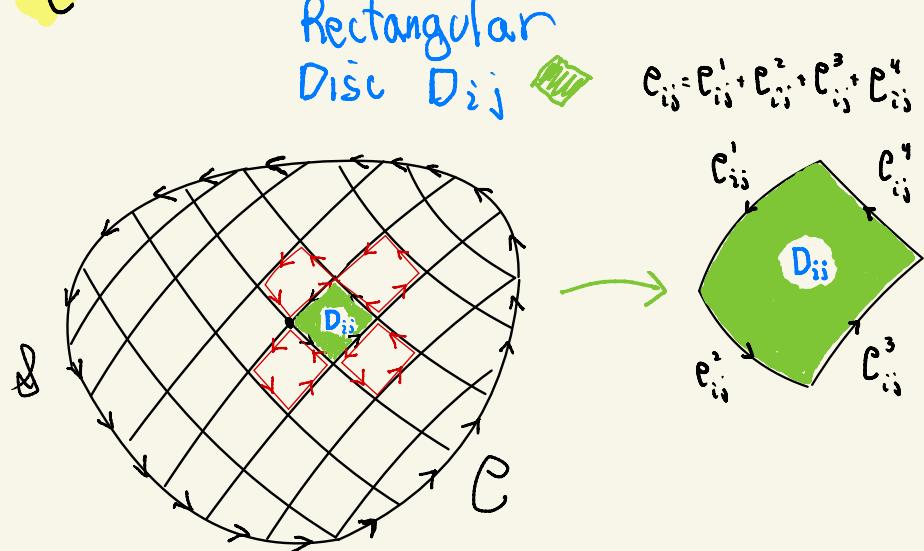
$$\text{I.e., } \iint_S \text{Curl} \vec{F} \cdot \vec{n} dS = \lim_{N \rightarrow \infty} \sum_{ij} \iint_{D_{ij}} \text{Curl} \vec{F} \cdot \vec{n} dS \xrightarrow{D_{ij} \xrightarrow{\perp} \int_{\partial D_{ij}} \vec{F} \cdot \vec{T} ds} |\partial D_{ij}|$$

$$= \lim_{N \rightarrow \infty} \sum_{ij} \int_{C_{ij}} \vec{F} \cdot \vec{T} ds \quad \begin{array}{l} \text{All adjacent line} \\ \text{integrals cancel} \\ \text{out leaving only} \\ \text{boundary} \end{array}$$

$$= \int_{\partial S} \vec{F} \cdot \vec{T} ds$$

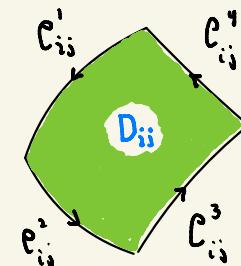


$$\vec{F}(u, v)$$



Rectangular Disc  $D_{ij}$

$$C_{ij} = C_{ij}^1 + C_{ij}^2 + C_{ij}^3 + C_{ij}^4$$



That is: all integrals on adjacent sides cancel out because they have opposite orientation, and the only line integrals left are the line integrals around outer boundary.

Note: This would be a proof, except we used Stokes Theorem to get  $\iint_S \text{Curl} \vec{F} \cdot \vec{n} dS = \int_{\partial S} \vec{F} \cdot \vec{T} ds$ ,

so we can't formally use that to prove Stokes Thm.

Conclude: the argument is circular in the sense that we assume Stokes Thm to interpret  $\text{Curl } \vec{F} \cdot \vec{n}$  as circulation per area, then use this to prove Stokes Thm - Even so, this is the correct intuition for why Stokes Thm is TRUE!